## **Probabilistic Model Checking**

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#### Part 8 - PTA Case Studies

## Overview

#### Discuss two real-world protocol examples

- modelled as probabilistic timed automata
- quantitatively analysed with PRISM
- compare experimental results (digital clocks, symbolic, sampling-based)

#### • IEEE 1394 FireWire root contention

- randomised leader election protocol, widely used
- confirmed a peculiarity...

#### IEEE 802.3 CSMA/CD

- distributed network arbitration protocol
- uses random backoff scheme, typical of Medium Access Control protocols

## IEEE 1394 (FireWire) root contention

- Serial bus for networking multimedia devices
  - "hot-pluggable" add/remove devices (nodes) at any time
- Root contention protocol
  - leader election algorithm, when nodes join/leave
  - nodes send messages: "be my parent"
  - root contention: when nodes contend leadership
  - random choice: "fast"/"slow" delay before retry
- Properties of interest
  - time taken for leader election
  - effect of using biased coin
  - conjecture [Sto02]





#### Typical FireWire configuration



#### FireWire initial configuration



# **FireWire Root Contention** Root contention

#### FireWire Root Contention



## FireWire – PRISM model

- Based on probabilistic timed automata (PTA) model
  - by Stoelinga et al. [SV99, SS01]
  - infinite state (real-time)
  - **concurrency**: messages between nodes and wires
  - underspecification of delays (upper/lower bounds)
  - probability: coin toss
- Applied three PTA model checking approaches
  - Symbolic forwards
  - Symbolic backwards
  - Digital clocks

#### FireWire - PTA model of a node

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#### FireWire - PTA model of the wire

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#### FireWire – Properties

Minimum probability that a leader is elected by time T

- $z.Pmin_{=?} [true U elected \land z \le T]$
- vary: T, coin bias: probability of choosing "fast"

#### Maximum expected time to elect a leader

- add reward structure for elapsed time
- assign reward one to each location
- Rmax<sub>=?</sub> [ F elected ]
- vary: coin bias
- only the digital clocks is applicable

#### FireWire – Results

- Minimum probability of electing leader by time T
  - $z.Pmin_{=?}$  [ true U elected  $\land z \leq T$  ]



#### FireWire – Results

- Maximum expected time to elect a leader
  - Rmax<sub>=?</sub> [ F elected ]



#### FireWire – Number of states

and the

time	backwards		forwards		digital clocks		
bound	states	size	states	size	states	size	
		(KB)		(KB)		(KB)	
2	1,219	7.24	825	18.9	80,980	554	
4	4,844	30.6	2,329	35.2	434,364	730	
6	10,981	55.0	3,833	51.9	1,093,658	860	
8	-	I	6,841	74.1	1,915,291	875	
10	-	-	9,661	90.1	2,746,691	875	
20	-		35,041	204	6,903,691	890	

#### FireWire – Computation time

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time	backwards	forwards		digital clocks		
bound	construct.	m/c	construct.	m/c	construct.	m/c
2	544+33.0	0.10	0.4+0.6	0.38	10.2	7.8
4	26,992+753	0.34	0.9+2.0	0.80	38.3	43
6	618,493+4,388	1.3	1.6+3.7	1.4	85.8	145
8	_	_	2.9+10	1.6	145	228
10	_	_	4.2+20	2.5	205	335
20	_	_	18+226	5.1	549	469

## Experimental results: CSMA/CD

- IEEE 802.3 CSMA/CD (Carrier Sense, Multiple Access with Collision Detection)
  - model of [NSY92], without probabilities
  - when a station has data to send, it listens to the medium
  - if the medium was free (no one transmitting), the station starts to send its data
  - if the medium was sensed busy, the station waits a random amount of time and then repeats this process
- Exponential backoff scheme
  - wait for a random delay between  $0, ..., 2^{k-1}$
  - where k counts number of collisions up to a bound K

#### CSMA/CD - PTA model of a station



#### CSMA/CD - PTA model of the medium

R. F.



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- Probability n collisions before a packet is sent (K=5)
  - $P_{=?}$  [ true U (collisions  $\ge n \land$  unsent) ]



- Probability n collisions before a packet is sent (K=10)
  - $P_{=?}$  [ true U (collisions  $\ge n \land$  unsent) ]



Probability packet is sent before time T (K=5)

- z.P<sub>=?</sub> [ true U (z $\leq$ T  $\land$  sent) ]



• Probability packet is sent before time T (K=10)

- z.P<sub>=?</sub> [ true U (z $\leq$ T  $\land$  sent) ]



Expected number of collisions before a packet is sent
 - R<sub>=?</sub> [F sent]



- Expected time until a packet is sent
  - $R_{=?}$  [ F sent ]

8



## Summing up...

- What have we achieved?
- Probabilistic timed automata
  - appropriate model for distributed coordination protocols that use randomisation
- Developed a methodology for quantitative analysis and verification
  - theory of probabilistic model checking: symbolic, digital clocks, sampling-based
  - resource usage and expectations
  - implementation of the techniques and experimental results

## Further information

- More on FireWire root contention
  - see [KNS03b,KNPS06,KNSW07]
- More on CSMA/CD
  - see [DKN+06]
- More on similar protocols
  - 802.11 WiFi [KNS03b]
  - IPv4 Zeroconf [KNS03b]
  - 802.15.4 Zigbee [Fru06]
- More information, see the PRISM web page
  www.prismmodelchecker.org